

sheet 3

exercise 1

1) Let's first examine $S_{2 \times 2}$: every hermitian matrix can be always written using the Pauli basis $(\mathbb{1}, \delta_x, \delta_y, \delta_z)$, where

$$\mathbb{1} = \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} \quad \delta_x = \begin{vmatrix} 0 & 1 \\ 1 & 0 \end{vmatrix} \quad \delta_y = \begin{vmatrix} 0 & -i \\ i & 0 \end{vmatrix} \quad \delta_z = \begin{vmatrix} 1 & 0 \\ 0 & -1 \end{vmatrix}$$

so, in general

$$\rho = \alpha \mathbb{1} + \sum_{\substack{\gamma \\ \gamma=x,y,z}} x_\gamma \delta_\gamma = \begin{vmatrix} \alpha + x_z & x_x - i x_y \\ x_x + i x_y & \alpha - x_z \end{vmatrix}$$

we require $\text{tr}(\rho) = 2\alpha = 1$, hence $\alpha = \frac{1}{2}$.

For convenience, define also the x_γ divided by 2, so that

$$\rho = \frac{1}{2} \left(\mathbb{1} + \sum_{\gamma=x,y,z} x_\gamma \delta_\gamma \right) = \frac{1}{2} \left(\mathbb{1} + \vec{x} \cdot \vec{\delta} \right)$$

where $\vec{x} = (x_x, x_y, x_z)$ can be seen as a vector in \mathbb{R}^3 .

$$\rho \geq 0 \iff \text{eig}(\rho) \geq 0$$

$$\det(\rho - \mu \mathbb{1}) = 0 \text{ yields } \mu = \frac{1}{2} \left(1 \pm \sqrt{\sum_\gamma x_\gamma^2} \right) \geq 0$$

$$\Downarrow \\ \|\vec{x}\| \leq 1$$

hence, this suggests the definition.

$$\begin{aligned} \phi: S_{\text{BLOCH}} &\rightarrow S_{2 \times 2} \\ \vec{x} &\mapsto \frac{1}{2} (\mathbb{1} + \vec{x} \cdot \vec{\delta}) \end{aligned}$$

obviously, $\phi(\vec{x}) \in S_{2 \times 2} \quad \forall \vec{x} \in S_{\text{BLOCH}}$

and as proven before, $\phi^{-1}(\rho(\vec{x})) \in S_{\text{BLOCH}}$

therefore ϕ is an isomorphism. □

2) $\rho \geq 0$, hence $\lambda_i \geq 0 \quad \forall$ eigenvalues of ρ

~~moreover, ρ is a convex combination of pure states~~

moreover, $\text{tr}(\rho) = \sum_i \lambda_i = 1$

hence, the only elements not representable as a convex combination of other elements are those with $\lambda_j = 1, \lambda_{i \neq j} = 0$ for $j = 1, \dots, \dim(\rho)$.

they correspond to the PURE STATES.

□

3) $0 \leq A \leq \mathbb{1}$

from $A \geq 0$ we have $\text{eig}(A)_i = \lambda_i \geq 0 \quad \forall i = 1, \dots, \dim(A)$

$A \leq \mathbb{1}; \mathbb{1} - A \geq 0$

for every λ_i , suppose the eigenvalue equation is

$$A x_i = \lambda_i x_i$$

$$\text{then, } (\mathbb{1} - A) x_i = (1 - \lambda_i) x_i \Rightarrow \lambda_i \leq 1 \quad \forall i$$

the whole condition is then

$$0 \leq \lambda_i \leq 1 \quad \forall i$$

the extremal points are then all the matrices whose eigenvalues are only 0 and 1.

□

exercise 2

\mathcal{C} is closed and bounded therefore, as we are in finite dimensions, it is compact.

This means that $\forall a \in \mathbb{R}^n$, $a \notin \mathcal{C}$ we can apply corollary 1.19 in the lecture notes:

$\forall a \in \mathbb{R}^n$, $a \notin \mathcal{C}$, \exists hyperplane separating \mathcal{C} and a strongly.

This hyperplane separates \mathbb{R}^n into two half-spaces, that can be characterised by ~~an~~ ^{two} inequalities. Call H_a the half-space s.t. $\mathcal{C} \subset H_a$.

Now define the set:

$$D := \bigcap_{a \notin \mathcal{C}} H_a, \text{ where the intersection is } \forall a \notin \mathcal{C}$$

then $\mathcal{C} \subseteq D$ by definition and, as \mathcal{C} is closed, $\mathcal{C} = D$.

□

Exercise 3

sheet 3

1) Let $S \subset \mathbb{R}^n$ convex. With this assumption, we want to prove:

$$f \text{ convex} \Leftrightarrow f((1-\lambda)x + \lambda y) \leq (1-\lambda)f(x) + \lambda f(y) \\ \forall x, y \in S; \forall \lambda \in [0, 1]$$

$$\Rightarrow) f \text{ convex} \Leftrightarrow \text{ep}(f) \text{ convex}$$

let $(x, f(x)), (y, f(y)) \in \text{ep}(f)$

by convexity of $\text{ep}(f)$:

$$((1-\lambda)x + \lambda y, \underbrace{(1-\lambda)f(x) + \lambda f(y)}_{\geq f((1-\lambda)x + \lambda y)}) \in \text{ep}(f) \quad \forall \lambda \in [0, 1] \\ \forall x, y \in S$$

$\Leftarrow)$ let the inequality hold.

then $(x, \mu_x), (y, \mu_y) \in \text{ep}(f)$. S convex, so

$$((1-\lambda)x + \lambda y, \mu \geq f((1-\lambda)x + \lambda y)) \in \text{ep}(f) \\ \forall x, y, \lambda$$

or the inequality for f holds, we can choose

$$\mu = (1-\lambda)\mu_x + \lambda\mu_y \geq (1-\lambda)f(x) + \lambda f(y) \geq f((1-\lambda)x + \lambda y)$$

hence $\text{ep}(f)$ is convex

$$\Downarrow \\ f \text{ convex}$$

□

2) Let's take a 1-dimensional open subset $(a, b) \subset \mathbb{R}^n$, then the result can be extended to higher-dimensional sets. Take $f: (a, b) \rightarrow \mathbb{R}$ convex; take also $x, z \in (a, b)$ $x < z$; then $\exists y \in (a, b) : x < y < z$.

$$f(y) = f((1-\lambda)x + \lambda z) \leq (1-\lambda)f(x) + \lambda f(z)$$

↑
ex. 3.1

$$\Leftrightarrow f(y) - f\left(\frac{x}{\lambda}\right) \leq -\lambda (f(x) - f(z)) \quad , \quad \lambda \in]0, 1[$$

let's take $\lambda := -\frac{y-x}{x-z}$; then

$$\frac{f(y) - f\left(\frac{x}{\lambda}\right)}{y-x} \leq \frac{f(x) - f(z)}{x-z} =: C \text{ constant } \forall y \in (x, z)$$

hence, we can always find a $C < \infty$ s.t.

$$|f(y) - f(x)| < C |x - y|$$

$\Rightarrow f$ is Lipschitz continuous

\Downarrow
 f continuous

□

exercise 4

1) $V \subseteq \mathbb{R}^n$, $\mathcal{C} \subset V$ convex, absorbing, balanced

First, note that ρ is well-defined as \mathcal{C} is absorbing.

To see that ρ is a seminorm, we have to prove:

$$\bullet \rho(\lambda x) = |\lambda| \rho(x) \quad \forall x \in V, \forall \lambda \in \mathbb{R}$$

$$\bullet \rho(x+y) \leq \rho(x) + \rho(y) \quad \forall x, y \in V$$

homogeneity: take $\lambda \geq 0$

$$\rho(\lambda x) = \inf \left\{ t \in \mathbb{R}^+ \mid \frac{\lambda x}{t} \in \mathcal{C} \right\} = \inf \left\{ t' \mid \frac{x}{t'} \in \mathcal{C} \right\} = \rho(x)$$

with $\frac{\lambda}{t} = \frac{1}{t'}$

$$\Rightarrow \rho(\lambda x) = \lambda \rho(x)$$

now take $\lambda < 0$, and note that \mathcal{C} balanced means

$$\rho(-x) = \rho(x). \text{ then}$$

$$\rho(-|\lambda|x) = \rho(|\lambda|x) = |\lambda| \rho(x)$$

triangle inequality: let's exploit the convexity in \mathcal{C} :

take $x, y \in \mathcal{C}$ and define $\rho(x) =: t$, $\rho(y) =: s$

$$\Rightarrow (1-\lambda) \frac{x}{t} + \lambda \frac{y}{s} \in \mathcal{C}$$

$$\text{choose } \lambda = \frac{s}{s+t}, \text{ so that: } \frac{x+y}{s+t} \in \mathcal{C}$$

now consider:

$$\rho(x+y) = \inf \left\{ \tilde{\lambda} \mid \frac{x+y}{\tilde{\lambda}} \in \mathcal{C} \right\} \leq s+t = \rho(x) + \rho(y)$$

□

2) Define the p -norm on $V = \mathbb{R}^n$: $\|x\|_p := \left(\sum_i |x_i|^p\right)^{1/p}$

Define the unit ball $B_1^p(0) := \{x \in V \mid \|x\|_p \leq 1\}$

convexity of B : B convex if it contains all the possible convex combinations of its points; take

$$z = \sum_j \lambda_j x_j, \quad x_j \in B \quad \forall j, \quad \sum_j \lambda_j = 1, \quad \lambda_j \in [0, 1]$$

$$\|z\|_p \leq \sum_j \lambda_j \|x_j\|_p \leq \sum_j \lambda_j = 1$$

$\Rightarrow z \in B \quad \forall$ convex comb. $\Rightarrow B$ convex

B absorbing: $x \in V, t \in \mathbb{R}^+$

$$tx \in B \iff \|tx\|_p = t \|x\|_p \leq 1$$

true for $t \leq \frac{1}{\|x\|_p}, \quad \forall x \in V$

B balanced: ~~recall~~ recall that B is convex

$$\text{take } x \in B \implies \|x\|_p = \|-x\|_p$$

$$x \in B \iff -x \in B$$

moreover, $\rho(x) = \|x\|_p$ or:

$$\begin{aligned} \rho(x) &= \inf \{t \in \mathbb{R}^+ \mid x \in tB\} = \\ &= \inf \{t \in \mathbb{R}^+ \mid \|x\|_p \leq t\} = \|x\|_p \end{aligned}$$

□